

NEMBot II PROGRAMMING SHEET

Desired Move	Step ROM Adr	Go Fwd 0 +	Go Back 100 +	distance (inches)	Turn Left 200 +	Turn Right 220 +	angle units angle/5	COMMAND
	30							poke 30 ,
	31							poke 31 ,
	34							poke 32 ,
	33							poke 33 ,
	34							poke 34 ,
	35							poke 35 ,
	36							poke 36 ,
	37							poke 37 ,
	38							poke 38 ,
	39							poke 39 ,
	40							poke 40 ,
	41							poke 41 ,
	42							poke 42 ,
	43							poke 43 ,
	44							poke 44 ,
	45							poke 45 ,
	46							poke 46 ,
	47							poke 47 ,
	48							poke 48 ,
	49							poke 49 ,
	50							poke 50 ,
	51							poke 51 ,
	52							poke 52 ,
	53							poke 53 ,
	54							poke 54 ,
	55							poke 55 ,
	56							poke 56 ,
	57							poke 57 ,
	58							poke 58 ,
	59							poke 59 ,
	60							poke 60 ,
	61							poke 61 ,
	62							poke 62 ,
	63							poke 63 ,
	64							poke 64 ,
	65							poke 65 ,

* 90 deg =18 45 deg=9
30 deg = 6

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